# SySCD A System-Aware Parallel Coordinate Descent Algorithm

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## Parallel Coordinate Descent

$$\min_{\alpha} f(A\alpha) + \sum_{i} g_i(\alpha_i)$$

#### Parallel Coordinate Descent

- 1: **Input:** Training data matrix  $A \in \mathbb{R}^{d \times n}$ Initial model  $\boldsymbol{\alpha} = \mathbf{0}, \mathbf{v} = \mathbf{0}$ 2: **for**  $t = 1, 2, \dots$  **do**
- 3: **parfor**  $j \in \text{RANDOMPERMUTATION}(n)$  **do**
- 4: Find  $\delta$  minimizing  $f(\mathbf{v} + A_{:,j}\delta) + g_j(\alpha_j + \delta)$
- 5:  $\alpha_j \leftarrow \alpha_j + \delta$
- 6:  $\mathbf{v} \leftarrow \mathbf{v} + \delta A_{:,j}$
- 7: end parfor
- 8: end for

## Parallel Coordinate Descent

$$\min_{\alpha} f(A\alpha) + \sum_{i} g_i(\alpha_i)$$

- Multi-core parallelism has previously been taken into account, e.g. [Hsieh'15]
- There are many more system bottlenecks one could incorporate into the algorithm design, i.e.,
  - 1. Inefficient cache accesses
  - 2. Write-contention on v
  - 3. Scalability across NUMA nodes

#### Parallel Coordinate Descent

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1: Input: Training data matrix A \in \mathbb{R}^{d \times n}
Initial model \alpha = \mathbf{0}, \mathbf{v} = \mathbf{0}
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2: for t = 1, 2, \dots do
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4: Find  $\delta$  minimizing  $f(\mathbf{v} + A_{:,j}\delta) + g_j(\alpha_j + \delta)$ 

```
5: \alpha_j \leftarrow \alpha_j + \delta
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6: 
$$\mathbf{v} \leftarrow \mathbf{v} + \delta A_{:,j}$$

7: end parfor

8: end for

→ SySCD addresses all of these

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3: **parfor**  $j \in \text{RANDOMPERMUTATION}(n)$  **do** 

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5:  $\alpha_j \leftarrow \alpha_j + \delta$ 

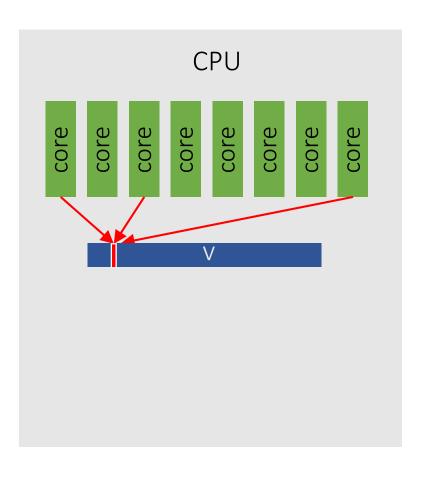
6:  $\mathbf{v} \leftarrow \mathbf{v} + \delta A_{:,j}$ 

7: end parfor

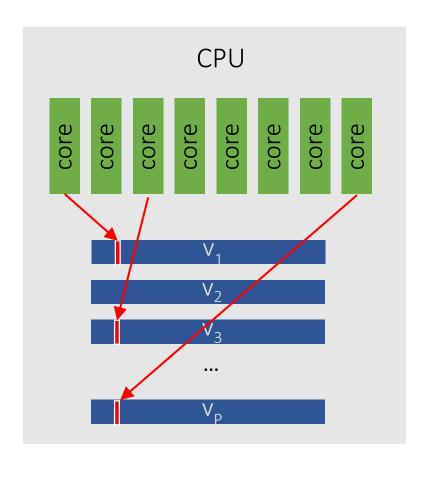
8: end for

→ SySCD addresses all of these

# Resolving write-contention on **v**



# Resolving write-contention on **v** → replicate **v** across threads



## Resolving write-contention on v

10: **end for** 

→ replicate **v** across threads

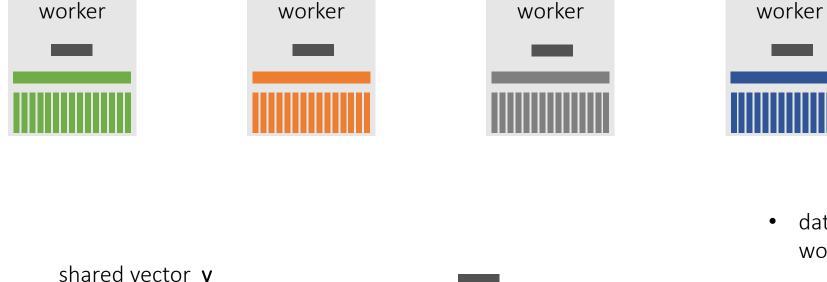
#### Parallel Coordinate Descent

```
1: Input: Training data matrix A \in \mathbb{R}^{d \times n}
                  Initial model \alpha = 0, \mathbf{v} = 0
2: for t = 1, 2, ... do # threads
    \mathbf{v}_p \leftarrow \mathbf{v} \quad \forall p \in [P]
4: parfor j \in \text{RANDOMPERMUTATION}(n) do
              Find \delta minimizing \hat{f}(\mathbf{v}_p, A_{:,j}, \alpha_j) + g_j(\alpha_j + \delta)
5:
             \alpha_j \leftarrow \alpha_j + \delta
6:
    \mathbf{v}_p \leftarrow \mathbf{v}_p + \delta A_{:,j}
                                                       auxiliary model inspired by CoCoA [Smith'18]
8: end parfor
     \mathbf{v} \leftarrow \sum_p \mathbf{v}_p
```

## Connection to Distributed Methods

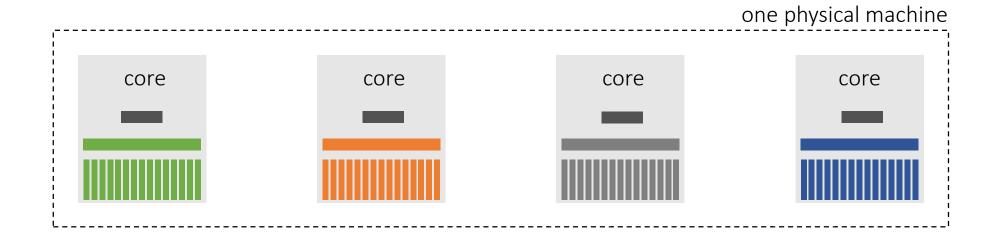
model lpha

data A



- data is partitioned across workers
- each worker has its own replica of the shared vector which is synchronized periodically

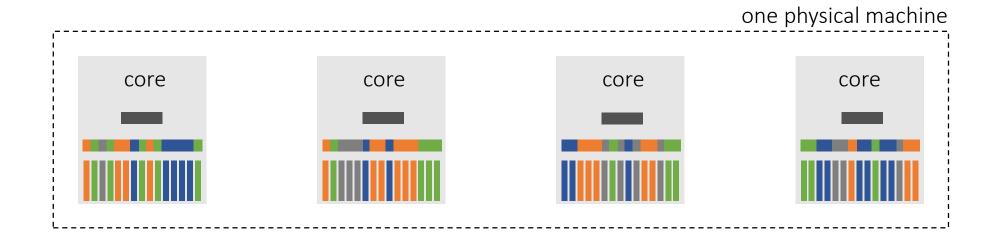
## Connection to Distributed Methods





- In the parallel setting a worker corresponds to a core
- Motivation of data separability is not communication-but implementation-efficiency

# Repartitioning





- In the parallel setting we can afford to repartition the data in each round
- ✓ Improved convergence behavior

# System-Aware Coordinate Descent (SySCD)

- Combination of distributed methods with repartitioning
  - ✓ high implementation efficiency
  - ✓ theoretically sound parallel method
  - ✓ scales to large degrees of parallelism
- Additional optimizations (not covered in this talk)
  - ✓ NUMA affinity
  - ✓ alignment with cache access pattern



